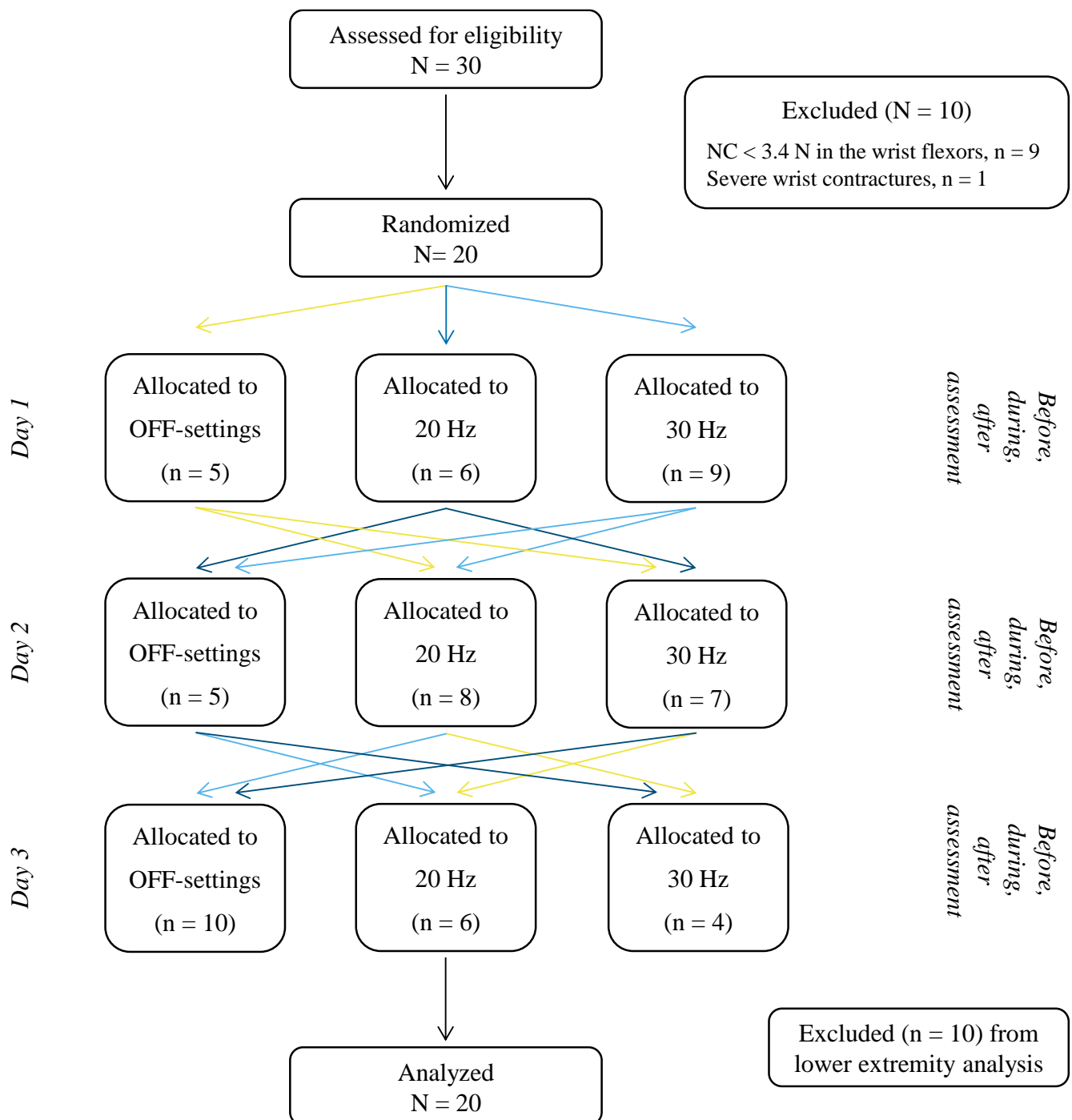


Supplementary Material

SUPPLEMENTARY FIGURE

Figure 1. Flow chart showing cross-over design and assessment points. NeuroFlexor neural component (NC), in Newton, N.



SUPPLEMENTARY MATERIALS AND METHODS

The NeuroFlexor model

The biomechanical model of the NeuroFlexor, previously described by Lindberg et al.(1), analyzes the resistive force resulting from passive wrist extension or dorsiflexion of the ankle at two velocities, and distinguishes the different contributions: inertia, elasticity, viscosity, and the neural component.

The inertia is the force resisting the acceleration of the hand or the foot.

The elastic component (EC) is a length-dependent resisting force to the stretch, and it is recorded 1 second after the end of the slow movement (at 5°/s).

The viscous component (VC) is a velocity-dependent resisting force produced by friction from neighboring tissues, for example sliding muscle fibers. VC is highest during the initial acceleration and continues at a lower level (approximately 20% of the early viscosity) during the fast movement at 236°/s for the upper extremity and 240°/s for the lower extremity.

Finally, the neural component (NC) is the stretch reflexes mediated force (i.e., spasticity) and it is estimated in the model at the maximal stretch by subtracting EC and VC from the total resistance.

Data on validity, reliability and sensitivity to change of the NeuroFlexor method have been described (1-3), and cut-off values for the passive and active contributions to increased upper limb muscle tone were defined (4).

SUPPLEMENTARY REFERENCE

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